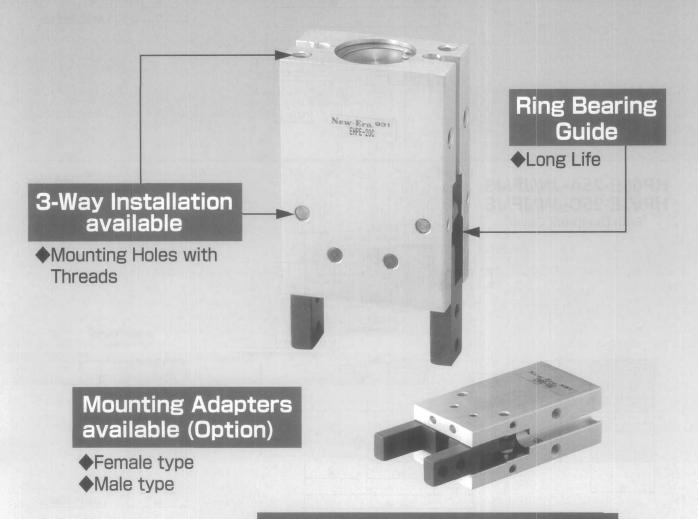
# EHPE Series Compact Gripper

# Improved Mechanism

♦High Rigidity (Repeat accuracy : below±0.01mm)

# Powerfull Gripping Force

**♦**Strong Closing Force by Extending Cylinder



# Straight and/or L-shaped ZE or ES type Sensor Switches

(Sensor switch is an option)

- **◆**detecting Levers OPEN
- **♦**detecting Levers CLOSED

# **Series**

#### Model Code No.

# PE - 10 C \* HAE - ZE255 A 2

Series Name

#### Nominal Size (Bore Size)

10:10mm 16:16mm 20:20mm 25:25mm

#### Action Type

A: Normally Open, Single Acting B: Normally Close, Single Acting (only for Custom-made)

C: Double Acting

Number of Switch

1:1 Switch 2:2 Switches

#### Switch Lead Wire

A:1m B:3m

(Option)

#### Sensor Switch Blank: without Switch Straight type

ES13, ZE135 : Solid state type, 2 wire ES15, ESP15, ZE155: Solid state type, 3 wire

L-shaped type

ES23, ZE235 : Solid state type, 2 wire ES25, ESP25, ZE255: Solid state type, 3 wire

(Option)

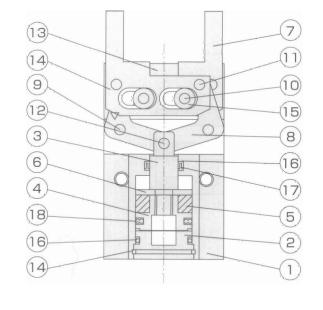
#### Mounting Adapter

Blank: without Adapter HAE: HAE type HFE: HFE type

HFEL: HFE-L type (only EHPE-16)

### Internal Structure

#### (Example: Double Acting type)



#### **Parts List**

No.	. Name Material		
1	Main Body	Aluminium Alloy	
2	Head Cover	Aluminium Alloy	
3	Piston Rod	Stainless Steel	
4	Piston	Aluminium Alloy	
5	Magnet	Plastic Magnet	
6	Holding Cover	Aluminium Alloy	
7	Lever	Carbon Tool Steel	
8	Action Lever	Carbon Steel	
9	Fulcrum Pin	Carbon Tool Steel	
10	Fulcrum Pin	Carbon Tool Steel	
11	Press-in Pin	Carbon Steel	
12	Press-in Pin	Carbon Steel	
13	Slide Plate	Carbon Steel	
14	Snap Ring	Hard Steel	
15	Ring	Carbon Steel	
16	O-ring	NBR	
17	Packing for Rod	NBR	
18	Packing for Piston	.NBR	

# **EHPE** Series

# Specifications

Action Type		Double Acting, Single Acting
Working Fluid		Air
Maximum Operating Pressure [I	MPa]	0.7
Proof Pressure [I	MPa]	1.05
Operating Ambient Temperature [	℃]	0 to 60
Lubrication		Not required (need for Levers sliding portion only)
Max.Operating Cycle [d	cycles per min.]	180 mmor or
Centering Accuracy [r	mm]	0.15 (+0.15 to -0.15)
Repeatability Accuracy [r	mm]	0.01 (+0.01 to -0.01)
Air port		M3×0.5 (EHPE-10) M5×0.8 (EHPE-16, EHPE-20, EHPE-25)
Available Switch type		ZE, ES type (Solid state type)

Action type	Model	Norminal Size [mm]	Minimum Operating Pressure [MPa]	Maximum Stroke [mm]	Effective Gripping Force [N]		Gripping Force (		Gripping Force		Stroke Gripping F		External Dimensions (Thick×Width×Length) [mm]	Weight [g]
	EHPE-10C	10	0.15	4	Close	8	16×23×44	47						
	EHPE-10C	10			Open	5								
	EHPE-16C	16	0.1	8	Close	24	22×34×55.5	100						
Double	ENPE-10C	10			Open	18		120						
Acting	EHPE-20C	20	0.1	12	Close	47	26×45×66.5	230						
		20			Open	35								
	EHPE-25C 25	25	5 0.1	14	Close	78	32×52×76.5	388						
		25			Open	60								
	EHPE-10A	10	0.35	4	Close	3	16×23×44	48						
		10			Open	2								
Single Acting, Normally Open	EHPE-16A 16 0.25	0.05	0	Close	13	22 24 25 5	101							
		10	0.25	8	Open	4	22×34×55.5	121						
	EUDE 20A	<b>EHPE-20A</b> 20 0.25	0.25	10	Close	23	000/45/00 5	220						
	EHPE-20A		12	Open	7	26×45×66.5	232							
	EHPE-25A	FUDE OF A	11	Close	38	00\/50\/70.5	200							
	ENFE-20A	25	0.25	14	Open	14	32×52×76.5	392						

Note: Effective Gripping Force (N) is the value at gripping point of 30 mm in length under operating pressure of 0.5MPa. Effective Gripping Force at Opening is shown by spring force for Single acting type of gripper.

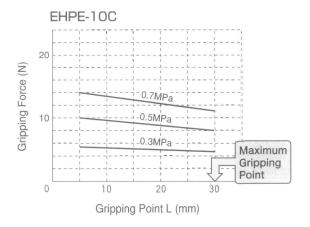
# **Mounting Adapter for Gripper**

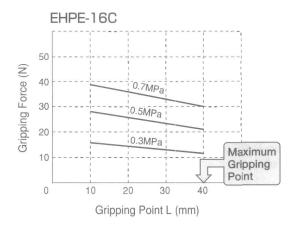
Gripper	Appli	cable Mounting Ada	pter
EHPE-10	HAE-10	HAE-10	
EHPE-16	HAE-16	HAE-16	HFE-16L
EHPE-20	HAE-20	HAE-20	-
EHPE-25	HAE-25	HAE-25	

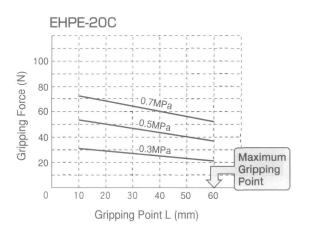
Please refer to the page 179 for "Dimensions of Mounting Adapter for Gripper".

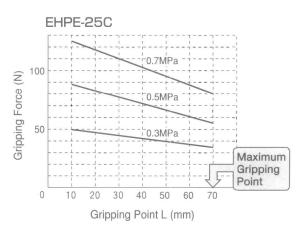
## **■**Effective Gripping Force

#### **(Double Acting Type)**









# ■ Calculation of Effective Gripping Force (When Opening):



Effective Gripping Force (when closing)

Gripping Point of Workpiece	Workpiece	(Attachment)
1		+
_		19
<u> </u>	++	Lever
	O abieto	

EHPE series	-10C	-16C	-20C	-25C
Cf	0.64	0.75	0.75	0.77

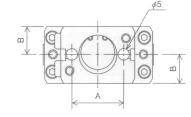
#### NOTE:

- 1. When gripping a workpiece, the mass of workpiece should be within the range between 5 to 10% of the above Effective Gripping Force.
- 2. When moving a workiece with gripping it, the mass of workpiece should be within the range between 2 to 4% of the above Effective Gripping Force.
- 3. The necessary gripping force depends on the material (surface) of workpiece, shape of fingers and moving speed and direction (horizontally or vertically) of gripper. Therefore, please take your operational condition into consideration.

# **EHPE** Series

#### Dimensions of Groove for Sensor Switch

				Unit: mr	
EHPE series	-10	-16	-20	-25	
Α	17	26	31	36	
В	8	11	13	16	

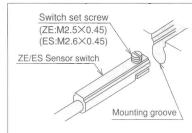


## Protruding Length of Switch

Refer to protruding length (L) of switch body from EHPE body at the levers closed fully.



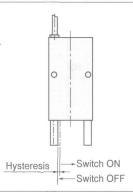
# Switch Installation



Insert switch into mounting groove. Locate in detecting position and then tighten set screw with miniature screwdriver up to 0.1N·m.

# Response Differential (Hysteresis)

This shows the stroke from the location where the lever moves and turns the switch ON to where the switch turns OFF in the opposite direction.



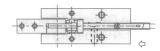
			Unit : mn		
EHPE series	-10	-16	-20	-25	
Max. Response Differential	0.3	0.4	0.4	0.4	
Operating Position Accuracy	0.2	0.2	0.2	0.2	

## Finding & Adjustment Ideal Detecting Position

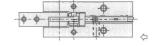
#### Levers-Inside Gripping (Workpiece-External Gripping)



①Check the levers are completely closed and inside gripping works.

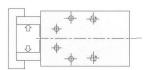


②Fit the switch into the groove in the direction of arrow. Continue inserting the switch further, then LED turns ON.

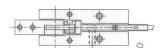


③Insert the switch in the direction of arrow by 0.6mm from position ② furthermore and fix it there with set screw.

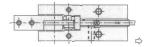
#### Levers-Outside Gripping (Workpiece-Internal Gripping)



①Check the levers are completely open and outside gripping works.



②Fit the switch into the groove in the direction of arrow. Continue inserting the switch further until LED turns ON. By moving it more, LED is OFF.



3 Move back the switch in the reverse direction of arrow by 0.6mm from position 2 furthermore and fix it there with set screw.

# New-Era.

#### Dimensions

EHPE-10A 48g EHPE-10C 47g M3×0.5

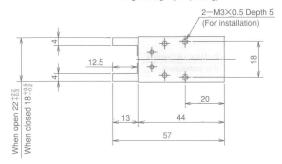
Double acting: Airport (Closing)

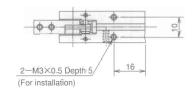
Single acting: Plug

7.5

Double acting: Airport (Opening)

Single acting: Airport (Closing)





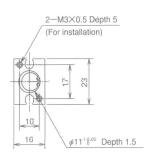
Unit : mm

#### Double Acting Type

Letters "C" and "O" are stamped near Air ports. Refer to each drawing which show Double acting type.

#### Single Acting Type

Only "C" is stamped at the same place of "O" for Double acting type, and the other port is pluged at factory.



Weight

EHPE-16A 121g EHPE-16C 120g

Og

M5×0.8

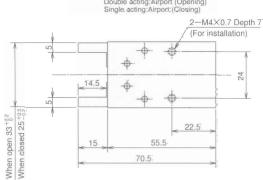
Double acting:Airport (Closing)

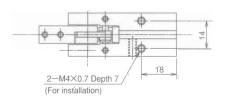
N5×0.8

Double acting:Plug

M5×0.8

Double acting:Airport (Opening)
Single acting:Airport:(Closing)





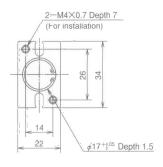
Unit: mm

#### **Double Acting Type**

Letters "C" and "O" are stamped near Air ports. Refer to each drawing which show Double acting type.

#### Single Acting Type

Only "C" is stamped at the same place of "O" for Double acting type, and the other port is pluged at:factory:



# EHPE Series

## **Dimensions**

Weight

EHPE-20A 232g EHPE-20C 230g

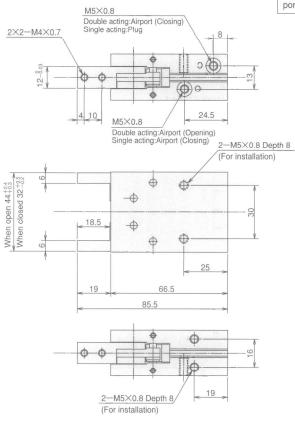
#### **Double Acting Type**

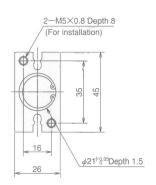
Letters "C" and "O" are stamped near Air ports. Refer to each drawing which show Double acting type.

#### Single Acting Type

Only "C" is stamped at the same place of "O" for Double acting type, and the other port is pluged at factory.

Unit: mm







### Dimensions

Weight

EHPE-25A 392g EHPE-25C 388g

#### Double Acting Type

Letters "C" and "O" are stamped near Air ports. Refer to each drawing which show Double acting type.

#### Single Acting Type

Only "C" is stamped at the same place of "O" for Double acting type, and the other port is pluged at factory.

Unit: mm

